

# Product data sheet

Specifications



## variable speed drive, Altivar Machine ATV340, 37kW, heavy duty, 400V, 3 phases, Ethernet

ATV340D37N4E

**Product availability: Stock - Normally stocked in distribution facility**

### Main

Range of Product	Altivar Machine ATV340
Product or Component Type	Variable speed drive
Product Specific Application	Machine
Mounting Mode	Wall mount
Variant	Standard version
Communication Port Protocol	Modbus TCP Modbus serial EtherNet/IP
Option card	communication module, PROFINET communication module, DeviceNet communication module, CANopen communication module, EtherCAT
Phase	3 phase
Supply frequency	50...60 Hz +/- 5 %
[Us] rated supply voltage	380...480 V - 15...10 %
nominal output current	74.5 A
Motor power kW	45 kW normal duty 37 kW heavy duty
Maximum Horse Power Rating	60 hp normal duty 50 hp heavy duty
EMC filter	Class C3 EMC filter integrated
IP degree of protection	IP20
Degree of protection	UL type 1

### Complementary

Discrete input number	8
Discrete input type	PT1 safe torque off 0...30 kHz, 24 V DC 30 V) DI1...DI5 programmable as pulse input, 24 V DC 30 V)3.5 kOhm programmable
number of preset speeds	16 preset speeds
Discrete output number	1.0
Discrete output type	Programmable output DQ1, DQ2 30 V DC 100 mA
Analogue input number	3
Analogue input type	AI1 software-configurable current 0...20 mA 250 Ohm 12 bits AI1 software-configurable temperature probe or water level sensor AI1 software-configurable voltage 0...10 V DC 31.5 kOhm 12 bits AI2 software-configurable voltage - 10...10 V DC 31.5 kOhm 12 bits

Price is "List Price" and may be subject to a trade discount – check with your local distributor or retailer for actual price.

<b>Analogue output number</b>	2
<b>Analogue output type</b>	Software-configurable voltage AQ1, AQ2 0...10 V DC 470 Ohm 10 bits Software-configurable current AQ1, AQ2 0...20 mA 500 Ohm 10 bits
<b>Relay output number</b>	3
<b>Output voltage</b>	<= power supply voltage
<b>Relay output type</b>	Relay outputs R1A Relay outputs R1C 100000 cycles Relay outputs R2A Relay outputs R2C 100000 cycles
<b>Maximum switching current</b>	Relay output R1C resistive, cos phi = 1 3 A 250 V AC Relay output R1C resistive, cos phi = 1 3 A 30 V DC Relay output R1C inductive, cos phi = 0.4 7 ms 2 A 250 V AC Relay output R1C inductive, cos phi = 0.4 7 ms 2 A 30 V DC Relay output R2C resistive, cos phi = 1 5 A 250 V AC Relay output R2C resistive, cos phi = 1 5 A 30 V DC Relay output R2C inductive, cos phi = 0.4 7 ms 2 A 250 V AC Relay output R2C inductive, cos phi = 0.4 7 ms 2 A 30 V DC
<b>Minimum switching current</b>	Relay output R1B 5 mA 24 V DC Relay output R2C 5 mA 24 V DC
<b>Physical interface</b>	2-wire RS 485
<b>Connector Type</b>	3 RJ45
<b>Method of access</b>	Slave Modbus RTU Slave Modbus TCP
<b>Transmission Rate</b>	4.8 kbit/s 9.6 kbit/s 19.2 kbit/s 38.4 kbit/s
<b>Transmission frame</b>	RTU
<b>Number of addresses</b>	1...247
<b>Data format</b>	8 bits, configurable odd, even or no parity
<b>Type of polarization</b>	No impedance
<b>4 quadrant operation possible</b>	True
<b>Asynchronous motor control profile</b>	Optimized torque mode Variable torque standard Constant torque standard
<b>Synchronous motor control profile</b>	Reluctance motor Permanent magnet motor
<b>Pollution degree</b>	2 IEC 61800-5-1
<b>Maximum output frequency</b>	0.599 kHz
<b>Acceleration and deceleration ramps</b>	Linear adjustable separately from 0.01...9999 s S, U or customized
<b>Motor slip compensation</b>	Adjustable Can be suppressed Automatic whatever the load Not available in permanent magnet motor law
<b>Switching frequency</b>	2...16 kHz adjustable 4...16 kHz with derating factor
<b>Nominal switching frequency</b>	4 kHz
<b>Braking to standstill</b>	By DC injection
<b>Brake chopper integrated</b>	True
<b>Line current</b>	79.8 A 380 V normal duty) 69.1 A 480 V normal duty) 67.1 A 380 V heavy duty) 59.0 A 480 V heavy duty)

<b>Line current</b>	79.8 A 380 V with internal line choke normal duty) 69.1 A 480 V with internal line choke normal duty) 67.1 A 380 V with internal line choke heavy duty) 59 A 480 V with internal line choke heavy duty) 67.1 A 59.0 A
<b>Maximum Input Current per Phase</b>	79.8 A
<b>Maximum output voltage</b>	480 V
<b>Apparent power</b>	57.4 kVA 480 V normal duty) 49.1 kVA 480 V heavy duty)
<b>Maximum transient current</b>	105.6 A 60 s normal duty) 105.6 A 2 s normal duty) 111.8 A 60 s heavy duty) 111.8 A 2 s heavy duty)
<b>Electrical connection</b>	Screw terminal 0.75...1.5 mm <sup>2</sup> control Screw terminal 35...50 mm <sup>2</sup> line side Screw terminal 35...50 mm <sup>2</sup> DC bus Screw terminal 50 mm <sup>2</sup> motor
<b>Prospective line Isc</b>	50 kA
<b>Base load current at high overload</b>	74.5 A
<b>Base load current at low overload</b>	88.0 A
<b>Power dissipation in W</b>	Natural convection 90 W 380 V 4 kHz heavy duty) Forced convection 796 W 380 V 4 kHz heavy duty) Natural convection 105 W 380 V 4 kHz normal duty) Forced convection 943 W 380 V 4 kHz normal duty)
<b>Electrical connection</b>	Control screw terminal 0.75...1.5 mm <sup>2</sup> AWG 18...AWG 16 Line side screw terminal 35...50 mm <sup>2</sup> AWG 2...AWG 1 DC bus screw terminal 35...50 mm <sup>2</sup> AWG 3...AWG 1 Motor screw terminal 50 mm <sup>2</sup> AWG 1
<b>With safety function Safely Limited Speed (SLS)</b>	True
<b>With safety function Safe brake management (SBC/SBT)</b>	True
<b>With safety function Safe Operating Stop (SOS)</b>	False
<b>With safety function Safe Position (SP)</b>	False
<b>With safety function Safe programmable logic</b>	False
<b>With safety function Safe Speed Monitor (SSM)</b>	False
<b>With safety function Safe Stop 1 (SS1)</b>	True
<b>With sft fct Safe Stop 2 (SS2)</b>	False
<b>With safety function Safe torque off (STO)</b>	True
<b>With safety function Safely Limited Position (SLP)</b>	False
<b>With safety function Safe Direction (SDI)</b>	False

<b>Protection type</b>	Thermal protection motor Safe torque off motor Motor phase loss motor Thermal protection drive Safe torque off drive Overheating drive Overcurrent drive Output overcurrent between motor phase and earth drive Output overcurrent between motor phases drive Short-circuit between motor phase and earth drive Short-circuit between motor phases drive Motor phase loss drive DC Bus overvoltage drive Line supply overvoltage drive Line supply undervoltage drive Input supply loss drive Exceeding limit speed drive Break on the control circuit drive
<b>Width</b>	8.4 in (213.0 mm)
<b>Height</b>	26.0 in (660.0 mm)
<b>Depth</b>	10.3 in (262.0 mm)
<b>Net Weight</b>	62.6 lb(US) (28.4 kg)
<b>Continuous output current</b>	88 A 4 kHz normal duty 74.5 A 4 kHz heavy duty

## Environment

<b>Operating altitude</b>	<= 4800 m with current derating above 1000m
<b>Operating position</b>	Vertical +/- 10 degree
<b>Product Certifications</b>	UL CSA TÜV EAC CTick
<b>Marking</b>	CE
<b>Standards</b>	IEC 61800-3 IEC 61800-5-1 IEC 60721-3 IEC 61508 IEC 13849-1 UL 618000-5-1 UL 508C IEC 61000-3-12
<b>Maximum THDI</b>	<48 % full load IEC 61000-3-12 <48 % 80 % load IEC 61000-3-12
<b>Assembly style</b>	With heat sink
<b>Electromagnetic compatibility</b>	Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6
<b>Environmental class (during operation)</b>	Class 3C3 according to IEC 60721-3-3 Class 3S3 according to IEC 60721-3-3
<b>Maximum acceleration under shock impact (during operation)</b>	150 m/s <sup>2</sup> at 11 ms
<b>Maximum acceleration under vibrational stress (during operation)</b>	10 m/s <sup>2</sup> at 13...200 Hz
<b>Maximum deflection under vibratory load (during operation)</b>	1.5 mm at 2...13 Hz
<b>Permitted relative humidity (during operation)</b>	Class 3K5 according to EN 60721-3
<b>Volume of cooling air</b>	63402.4 Gal/hr(US) (240.0 m <sup>3</sup> /h)

Type of cooling	Forced convection
Overvoltage category	Class III
Regulation loop	Adjustable PID regulator
Noise level	63.5 dB
Pollution degree	2
Ambient air transport temperature	-40...158 °F (-40...70 °C)
Ambient air temperature for operation	5...122 °F (-15...50 °C) without derating vertical position 122...140 °F (50...60 °C) with derating factor vertical position
Ambient Air Temperature for Storage	-40...158 °F (-40...70 °C)
Isolation	Between power and control terminals

## Ordering and shipping details

Category	US1CP4B22183
Discount Schedule	CP4B
GTIN	3606480967108
Returnability	Yes
Country of origin	CN

## Packing Units

Unit Type of Package 1	PCE
Nbr. of units in pkg.	1
Package 1 Height	22.047 in (56.000 cm)
Package 1 Width	13.386 in (34.000 cm)
Package 1 Length	33.071 in (84.000 cm)
Package weight(Lbs)	79.366 lb(US) (36.000 kg)

## Contractual warranty

Warranty (in months)	18
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## Environmental Data

Schneider Electric aims to achieve Net Zero status by 2050 through supply chain partnerships, lower impact materials, and circularity via our ongoing "Use Better, Use Longer, Use Again" campaign to extend product lifetimes and recyclability.

[Environmental Data explained >](#)

[How we assess product sustainability >](#)

### Environmental footprint

Carbon footprint (kg CO2 eq, Total Life cycle)	27301
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## Use Better

### Materials and Substances

Packaging made with recycled cardboard	Yes
Packaging without single use plastic	No
<a href="#">EU RoHS Directive</a>	Pro-active compliance (Product out of EU RoHS legal scope)
SCIP Number	8ac43dc1-9e7e-4e1a-a3ee-665587b07cd7
REACH Regulation	<a href="#">REACH Declaration</a>
California proposition 65	<b>WARNING:</b> This product can expose you to chemicals including: Lead and lead compounds, which is known to the State of California to cause cancer and birth defects or other reproductive harm. For more information go to <a href="http://www.P65Warnings.ca.gov">www.P65Warnings.ca.gov</a>

### Energy efficiency

Product contributes to saved and avoided emissions	Yes
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## Use Longer

### Lifetime extension

Repair	No
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## Use Again

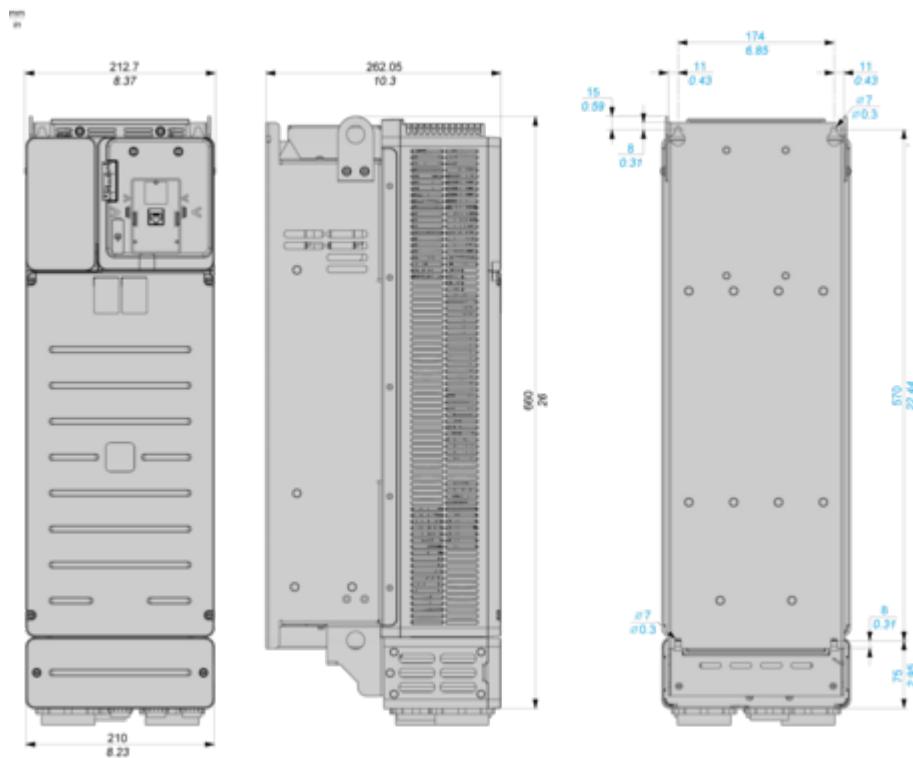
### Repack and remanufacture

Take-back	No
WEEE Label	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins.

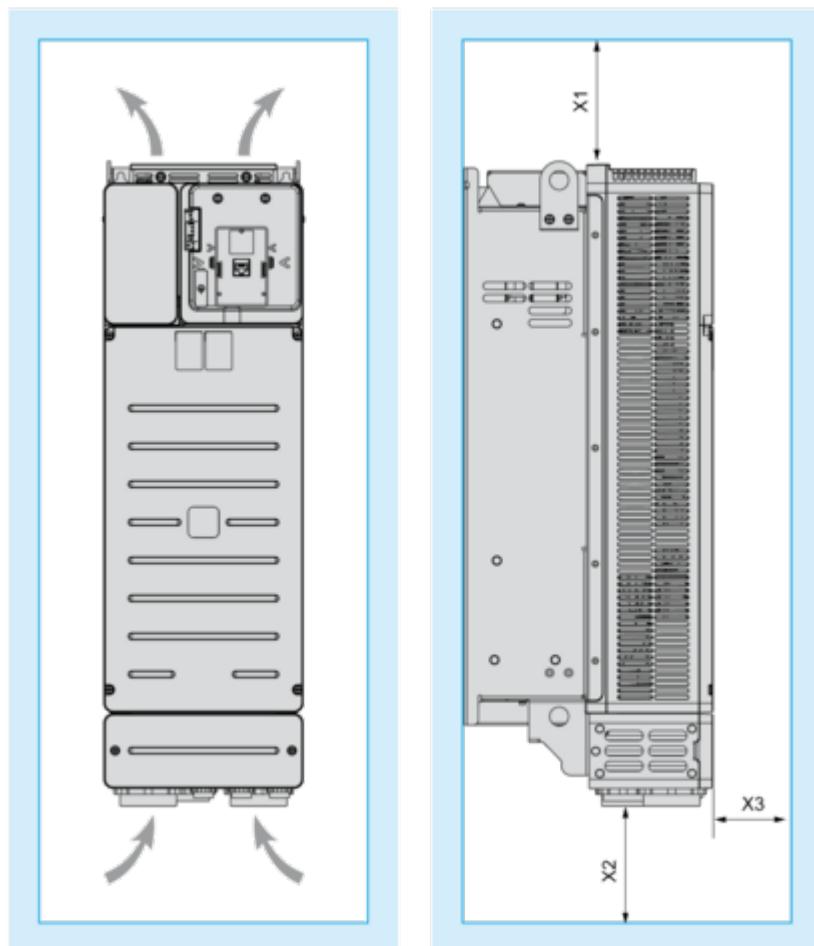
## Dimensions Drawings

## Dimensions

## Views: Front - Left - Rear

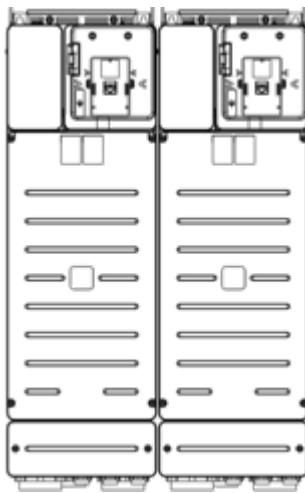


## Mounting and Clearance

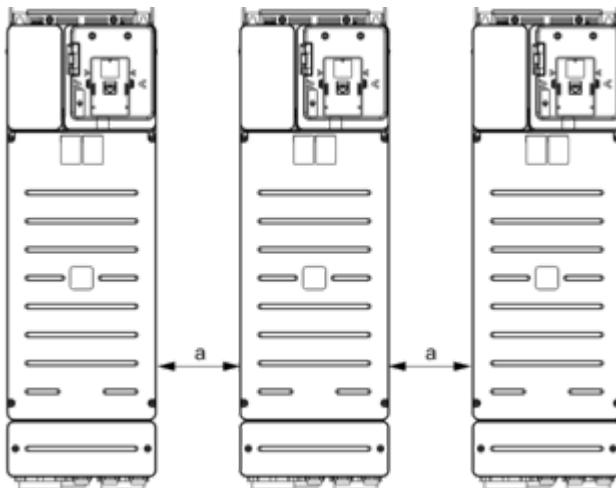
Clearance

X1	X2	X3			
mm	in.	mm	in.	mm	in.
≥ 100	≥ 3.94	≥ 100	≥ 3.94	≥ 10	≥ 0.39

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**Mounting Types****Mounting Type A: Side by Side IP20**

Possible, up to 50 °C, 2 drives only

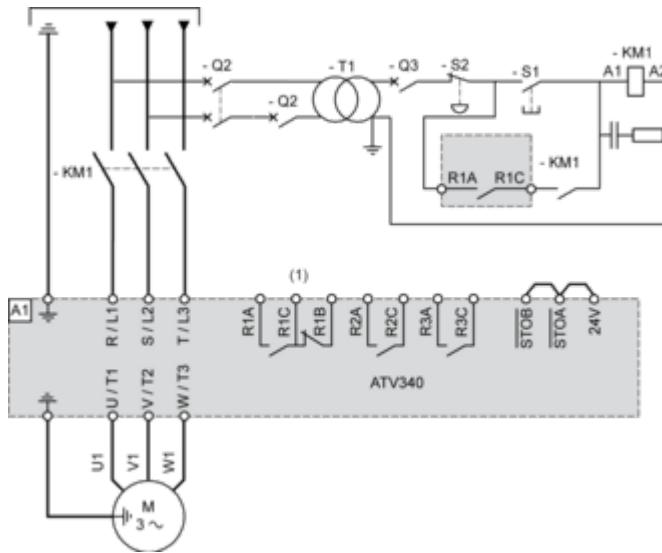
**Mounting Type B: Individual IP20**

$a \geq 110 \text{ mm (4.33 in.)}$

## Connections and Schema

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## Three-phase Power Supply - Diagram With Line Contactor

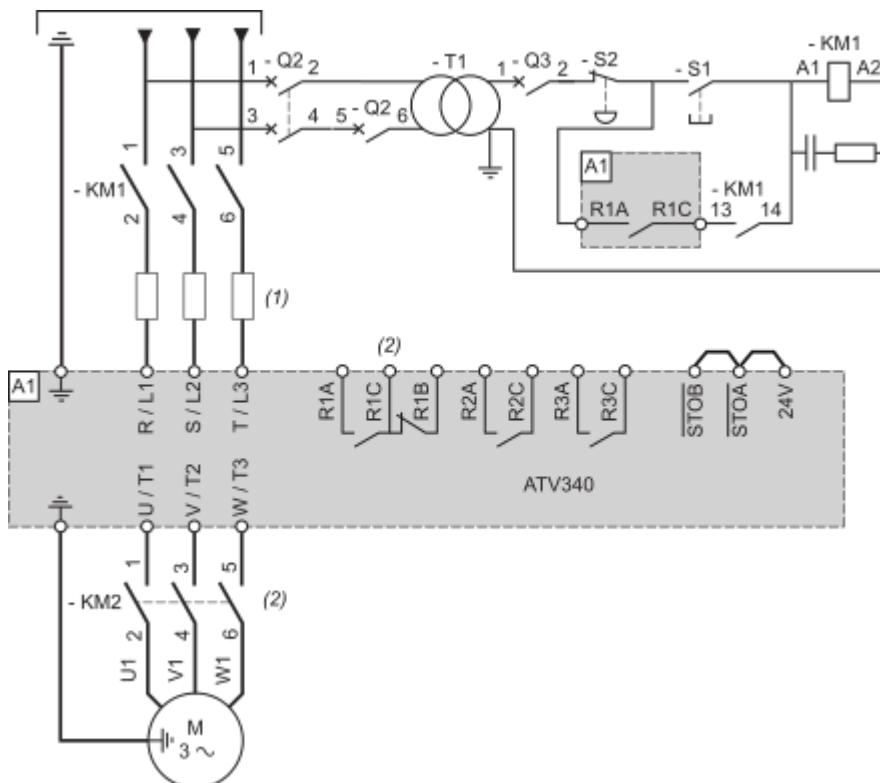


(1) : Use relay output R1 set to operating state Fault to switch Off the product once an error is detected.

**NOTE :**

- Press S1 until the initialization of the drive is finished.
- An external 24V power supply can be connected so that the control part of the drive is always power supplied.

## Three-phase Power Supply - Diagram With Downstream Contactor

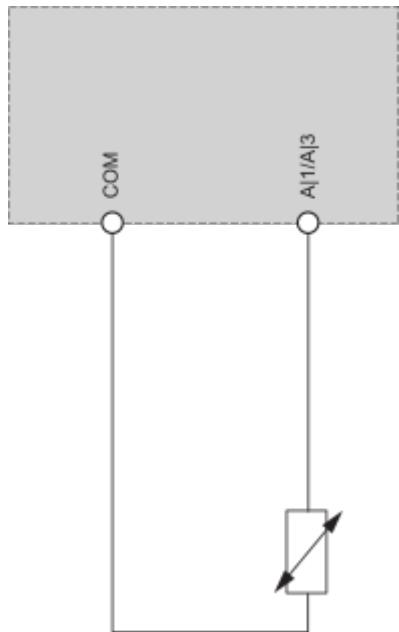


(1) : Use relay output R1 set to operating state Fault to switch Off the product once an error is detected.

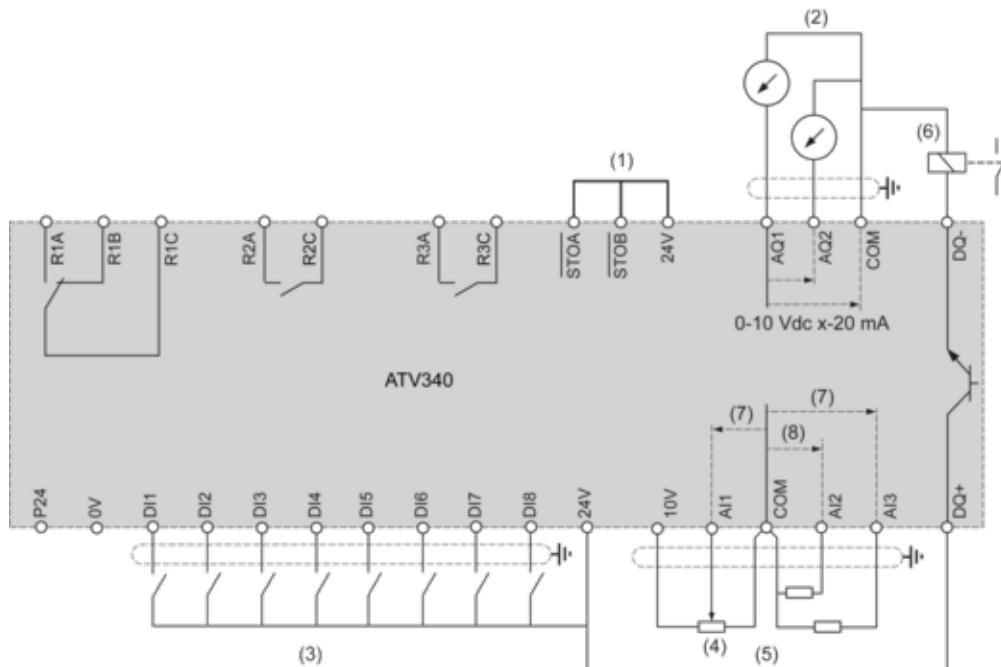
(2) : Command of KM2 can be done by using the [Output contactor cmd] OCC function. For more information, refer to the programming manual.

**NOTE :**

- Close upstream contactor, then press S1 after the initialization of the drive is finished.
- An external 24V power supply can be connected so that the control part of the drive is always power supplied.

**Sensor Connection**

## Control Block Wiring Diagram



(1) : STO Safe Torque Off

(2) : Analog Output

(3) : Digital Input - Shielding instructions are given in the Electromagnetic Compatibility section

(4) : Reference potentiometer (ex. SZ1RV1002)

(5) : Analog Input

(6) : Digital output

(7) : 0-10 Vdc, x-20 mA

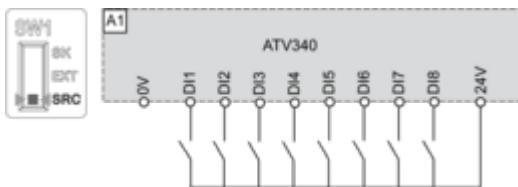
(8) : 0-10 Vdc, -10 Vdc...+10 Vdc

NOTE : PTI function is not available on frame sizes 4 and 5.

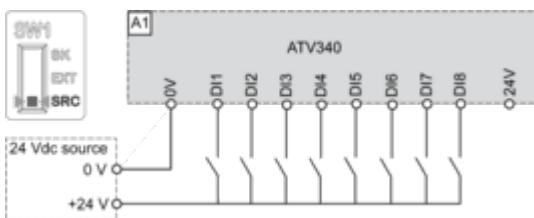
### Digital Inputs Wiring

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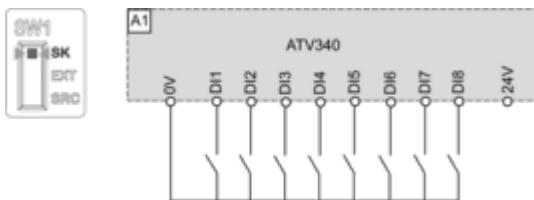
#### Switch Set to SRC (Source) Position Using the Output Power Supply for the Digital Inputs



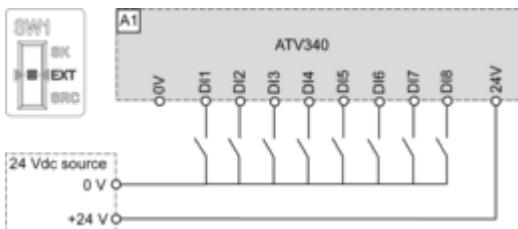
#### Switch Set to SRC (Source) Position and Use of an External Power Supply for the DI



#### Switch Set to SK (Sink) Position Using the Output Power Supply for the Digital Inputs



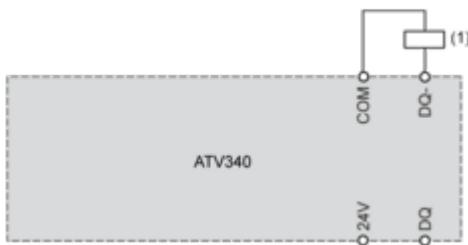
#### Switch Set to EXT Position Using an External Power Supply for the DI



### Digital Outputs Wiring

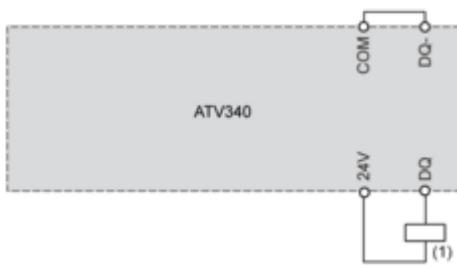
#### **Digital Outputs: Internal Supply**

Positive Logic, Source, European Style, DQ switches to +24V



(1) Relay or valve

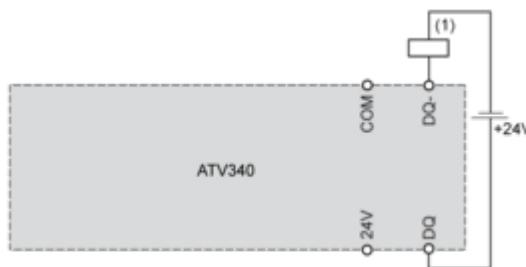
Negative Logic, Sink, Asian Style, DQ switches to 0V



(1) Relay or valve

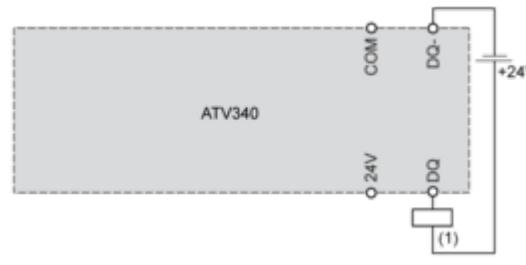
#### **Digital Outputs: External Supply**

Positive Logic, Source, European Style, DQ switches to +24V



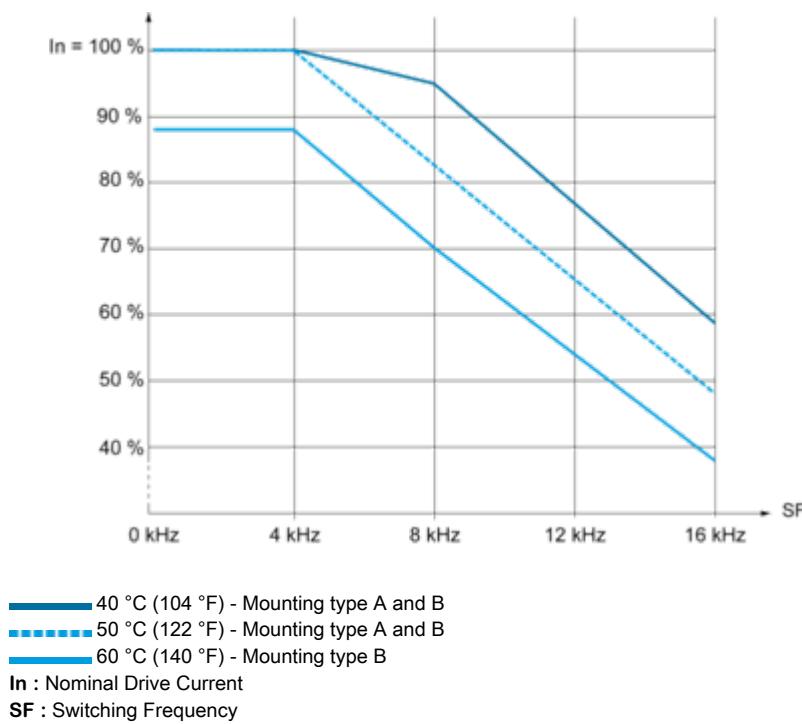
(1) Relay or valve

Negative Logic, Sink, Asian Style, DQ switches to 0V



(1) Relay or valve

## Performance Curves

Derating Curves

## Technical Illustration

## Dimensions

