

Product datasheet

Specifications



variable speed drive, Altivar Process
ATV900, floor standing ATV950,
110kW, 400 to 440V, without
braking unit, IP54

ATV950C11N4F

Main

Range of product	Altivar Process ATV900
Product specific application	Process for industrial
Product or component type	Variable speed drive
Variant	With load break switch Without braking chopper
Device application	Industrial application
Product destination	Synchronous motors Asynchronous motors
Network number of phases	3 phases
mounting mode	Floor-standing
Continuous output current	211 A at 2.5 kHz for normal duty 173 A at 2.5 kHz for heavy duty
Communication port protocol	Modbus serial EtherNet/IP Modbus TCP
option module	Slot A: communication module for Profibus DP V1 Slot A: communication module for PROFINET Slot A: communication module for DeviceNet Slot A: communication module for EtherCAT Slot A: communication module for CANopen daisy chain RJ45 Slot A: communication module for CANopen SUB-D 9 Slot A: communication module for CANopen screw terminals Slot A/slot B/slot C: digital and analog I/O extension module Slot A/slot B/slot C: output relay extension module Slot B: 5/12 V digital encoder interface module Slot B: analog encoder interface module Slot B: resolver encoder interface module communication module for Ethernet Powerlink
[Us] rated supply voltage	380...440 V - 15...10 %
[Us] rated supply voltage	380...440 V
Relative symmetric mains voltage tolerance	10 %
Relative symmetric network frequency tolerance	5 %
nominal output current	211.0 A
Motor power kW	110.0 kW for normal duty 90.0 kW for heavy duty
EMC filter	Integrated With EMC plate option
IP degree of protection	IP54

Complementary

Price is "List Price" and may be subject to a trade discount – check with your local distributor or retailer for actual price.

Disclaimer: This documentation is not intended as a substitute for and is not to be used for determining suitability or reliability of these products for specific user applications

Electrical connection	Control: removable screw terminals 0.5...1.5 mm² Line side: M12 bar Motor: M12 bar
Transmission rate	10/100 Mbit/s for Ethernet IP/Modbus TCP 4.8, 9.6, 19.2, 38.4 kbit/s for Modbus serial
Exchange mode	Half duplex, full duplex, autonegotiation Ethernet IP/Modbus TCP
Data format	8 bits, configurable odd, even or no parity for Modbus serial
Type of polarization	No impedance for Modbus serial
Number of addresses	1...247 for Modbus serial
Supply	External supply for digital inputs: 24 V DC (19...30 V), <1.25 mA, protection type: overload and short-circuit protection Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V DC +/- 5 %, <10 mA, protection type: overload and short-circuit protection Internal supply for digital inputs and STO: 24 V DC (21...27 V), <200 mA, protection type: overload and short-circuit protection
Local signalling	Local diagnostic: 3 LED (mono/dual colour) Embedded communication status: 5 LED (dual colour) Communication module status: 2 LED (dual colour) Presence of voltage: 1 LED (red)
Input compatibility	DI1...DI8: discrete input level 1 PLC conforming to IEC 61131-2 DI7, DI8: pulse input level 1 PLC conforming to IEC 65A-68 STOA, STOB: discrete input level 1 PLC conforming to IEC 61131-2
Discrete input logic	Positive logic (source) (DI1...DI8), < 5 V (state 0), > 11 V (state 1) Negative logic (sink) (DI1...DI8), > 16 V (state 0), < 10 V (state 1) Positive logic (source) (DI7, DI8), < 0.6 V (state 0), > 2.5 V (state 1) Positive logic (source) (STOA, STOB), < 5 V (state 0), > 11 V (state 1)
Sampling duration	2 ms +/- 0.5 ms (DI1...DI8) - discrete input 5 ms +/- 1 ms (DI7, DI8) - pulse input 1 ms +/- 1 ms (AI1, AI2, AI3) - analog input 5 ms +/- 1 ms (AQ1, AQ2) - analog output
Accuracy	+/- 0.6 % AI1, AI2, AI3 for a temperature variation 60 °C analog input +/- 1 % AQ1, AQ2 for a temperature variation 60 °C analog output
Linearity error	AI1, AI2, AI3: +/- 0.15 % of maximum value for analog input AQ1, AQ2: +/- 0.2 % for analog output
Refresh time	Relay output (R1, R2, R3): 5 ms (+/- 0.5 ms)
Isolation	Between power and control terminals
Discrete input number	10
Discrete input type	DI1...DI8 programmable, 24 V DC (<= 30 V), impedance: 3.5 kOhm DI7, DI8 programmable as pulse input: 0...30 kHz, 24 V DC (<= 30 V) STOA, STOB safe torque off, 24 V DC (<= 30 V), impedance: > 2.2 kOhm
Discrete output number	2
Discrete output type	Logic output DQ+ 0...1 kHz <= 30 V DC 100 mA Programmable as pulse output DQ+ 0...30 kHz <= 30 V DC 20 mA Logic output DQ- 0...1 kHz <= 30 V DC 100 mA
Analogue input number	3
Analogue input type	AI1, AI2, AI3 software-configurable voltage: 0...10 V DC, impedance: 30 kOhm, resolution 12 bits AI1, AI2, AI3 software-configurable current: 0...20 mA/4...20 mA, impedance: 250 Ohm, resolution 12 bits
Analogue output number	2
Analogue output type	Software-configurable voltage AQ1, AQ2: 0...10 V DC impedance 470 Ohm, resolution 10 bits Software-configurable current AQ1, AQ2: 0...20 mA impedance 500 Ohm, resolution 10 bits
Relay output number	3

Relay output type	Configurable relay logic R1: fault relay NO/NC electrical durability 100000 cycles Configurable relay logic R2: sequence relay NO electrical durability 1000000 cycles Configurable relay logic R3: sequence relay NO electrical durability 1000000 cycles
Maximum switching current	Relay output R1 on resistive load, cos phi = 1: 3 A at 250 V AC Relay output R1 on resistive load, cos phi = 1: 3 A at 30 V DC Relay output R1 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R1 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC Relay output R2, R3 on resistive load, cos phi = 1: 5 A at 250 V AC Relay output R2, R3 on resistive load, cos phi = 1: 5 A at 30 V DC Relay output R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC
Minimum switching current	Relay output R1, R2, R3: 5 mA at 24 V DC
Discrete input logic	16 preset speeds
Physical interface	Ethernet 2-wire RS 485
Connector type	2 RJ45 1 RJ45
Method of access	Slave Modbus TCP
Transmission rate	10, 100 Mbits 4.8 kbps 9600 bit/s 19200 bit/s
Transmission frame	RTU
Number of addresses	1...247
Data format	8 bits, configurable odd, even or no parity
Type of polarization	No impedance
4 quadrant operation possible	False
Asynchronous motor control profile	Constant torque standard Optimized torque mode Variable torque standard
Synchronous motor control profile	Permanent magnet motor Synchronous reluctance motor
Maximum output frequency	599 Hz
Acceleration and deceleration ramps	Linear adjustable separately from 0.01...9999 s
Motor slip compensation	Not available in permanent magnet motor law Can be suppressed Adjustable Automatic whatever the load
Switching frequency	2.5...8 kHz with derating factor 2...8 kHz adjustable
Nominal switching frequency	2.5 kHz
Braking to standstill	By DC injection
Brake chopper integrated	False
Line current	207.0 A at 380 V (normal duty) 174.0 A at 380 V (heavy duty) 179.0 A at 440 V (normal duty) 151.0 A at 440 V (heavy duty)
Maximum input current	207.0 A
Maximum output voltage	440.0 V
Apparent power	135 kVA at 400 V (normal duty) 113 kVA at 400 V (heavy duty)
Maximum transient current	253 A during 60 s (normal duty) 260 A during 60 s (heavy duty)

Network frequency	50...60 Hz
Prospective line Isc	50 kA
Base load current at high overload	173.0 A
Base load current at low overload	211.0 A
Power dissipation in W	2530 W, switching frequency 2.5 kHz (normal duty) 2010 W, switching frequency 2.5 kHz (heavy duty)
With safety function Safely Limited Speed (SLS)	True
With safety function Safe brake management (SBC/SBT)	True
With safety function Safe Operating Stop (SOS)	False
With safety function Safe Position (SP)	False
With safety function Safe programmable logic	False
With safety function Safe Speed Monitor (SSM)	False
With safety function Safe Stop 1 (SS1)	True
With sft fct Safe Stop 2 (SS2)	False
With safety function Safe torque off (STO)	True
With safety function Safely Limited Position (SLP)	False
With safety function Safe Direction (SDI)	False
Protection type	Thermal protection: motor Safe torque off: motor Motor phase break: motor Thermal protection: drive Safe torque off: drive Overheating: drive Overcurrent between output phases and earth: drive Overload of output voltage: drive Short-circuit protection: drive Motor phase break: drive Overvoltages on the DC bus: drive Line supply overvoltage: drive Line supply undervoltage: drive Line supply phase loss: drive Overspeed: drive Break on the control circuit: drive
Quantity per set	1
Width	400 mm
Height	2350 mm
Depth	669 mm
Product weight	330 kg

Environment

Insulation resistance	> 1 MOhm 500 V DC for 1 minute to earth
Noise level	69 dB conforming to 86/188/EEC
Vibration resistance	1.5 mm peak to peak (f= 2...13 Hz) conforming to IEC 60068-2-6 1 gn (f= 13...200 Hz) conforming to IEC 60068-2-6
Shock resistance	15 gn for 11 ms conforming to IEC 60068-2-27
Environmental characteristic	Chemical pollution resistance class 3C3 conforming to IEC 60721-3-3 Dust pollution resistance class 3S3 conforming to IEC 60721-3-3
Relative humidity	5...95 % without condensation conforming to IEC 60068-2-3

Ambient air temperature for operation	-15...40 °C (without derating) 40...50 °C (with derating factor)
Operating altitude	<= 1000 m without derating 1000...4800 m with current derating 1 % per 100 m
Operating position	Vertical +/- 10 degree
Product certifications	ATEX EAC C-Tick
Marking	CE
Standards	IEC 60204-1 IEC 61800-2 IEC 61800-3 IEC 61800-5-1
Maximum THDI	<48 % full load conforming to IEC 61000-3-12
Assembly style	In floor-standing enclosure
Electromagnetic compatibility	Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6
Environmental class (during operation)	Class 3C3 according to IEC 60721-3-3 Class 3S3 according to IEC 60721-3-3
Maximum acceleration under shock impact (during operation)	150 m/s² at 11 ms
Maximum acceleration under vibrational stress (during operation)	10 m/s² at 13...200 Hz
Maximum deflection under vibratory load (during operation)	1.5 mm at 2...13 Hz
Permitted relative humidity (during operation)	Class 3K5 according to EN 60721-3
Volume of cooling air	720 m3/h
Overvoltage category	III
Regulation loop	Adjustable PID regulator
Noise level	69 dB
Pollution degree	2
Ambient air transport temperature	-40...70 °C
Ambient air temperature for storage	-40...70 °C

Packing Units

Unit Type of Package 1	PCE
Number of Units in Package 1	1
Package 1 Height	238.5 cm
Package 1 Width	120.0 cm
Package 1 Length	110.0 cm
Package 1 Weight	370.0 kg

Contractual warranty

Warranty (in months)	18
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Environmental Data

Schneider Electric aims to achieve Net Zero status by 2050 through supply chain partnerships, lower impact materials, and circularity via our ongoing “Use Better, Use Longer, Use Again” campaign to extend product lifetimes and recyclability.

[Environmental Data explained >](#)

[How we assess product sustainability >](#)



Environmental footprint

Total lifecycle Carbon footprint	91 925 kg CO2 eq.
Carbon footprint of the manufacturing phase [A1 to A3]	2 134 kg CO2 eq.
Carbon footprint of the distribution phase [A4]	62 kg CO2 eq.
Carbon footprint of the installation phase [A5]	0 kg CO2 eq.
Carbon footprint of the use phase [B2, B3, B4, B6]	89 706 kg CO2 eq.
Carbon footprint of the end-of-life phase [C1 to C4]	24 kg CO2 eq.
Environmental Disclosure	Product Environmental Profile

Use Better



Materials and Substances

Packaging made with recycled cardboard	No
Packaging without single use plastic	No
SCIP Number	0e5fd009-2e67-4caa-9200-f008c39b3a95
EU RoHS Directive	Compliant By Exemption
REACH Regulation	Reference contains Substances of Very High Concern above the threshold



Energy efficiency

Product contributes to saved and avoided emissions	Yes
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Use Longer



Lifetime extension

Repair	No
Product repair index	A

Use Again



Repack and remanufacture

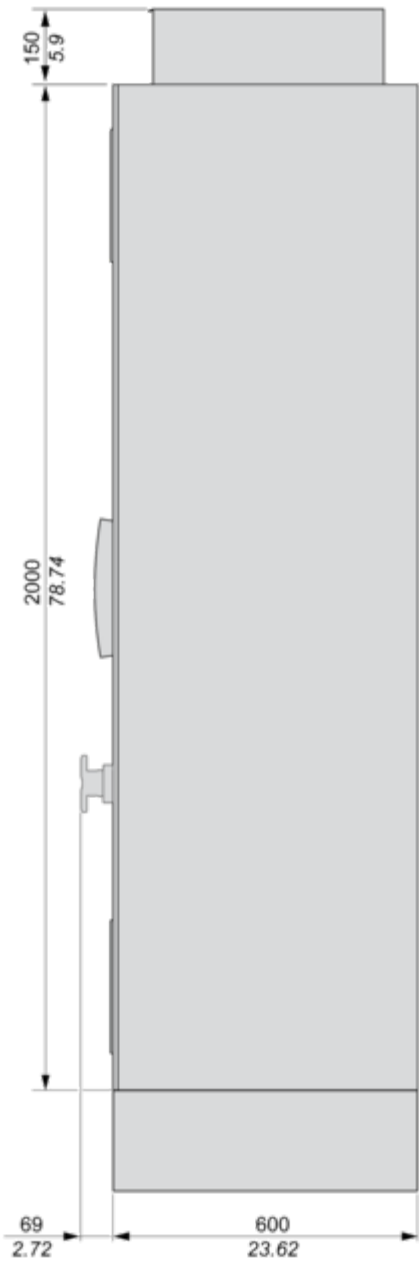
End of life manual availability	End of Life Information
Take-back	No

Dimensions Drawings

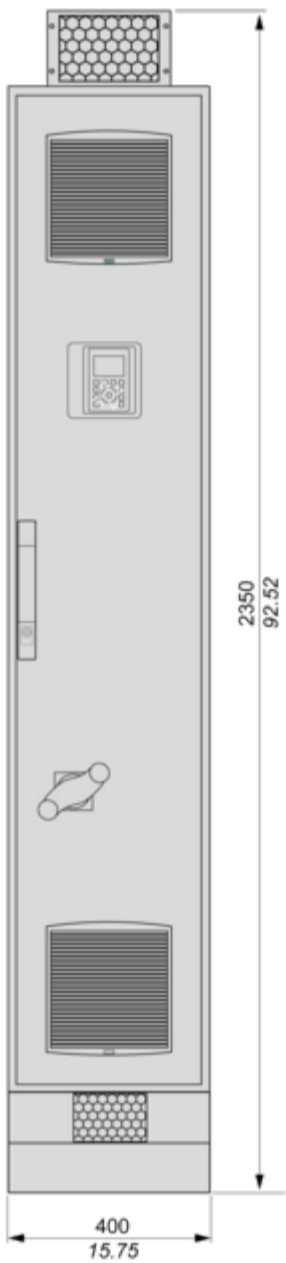
Dimensions

Right and Front View

mm
in.

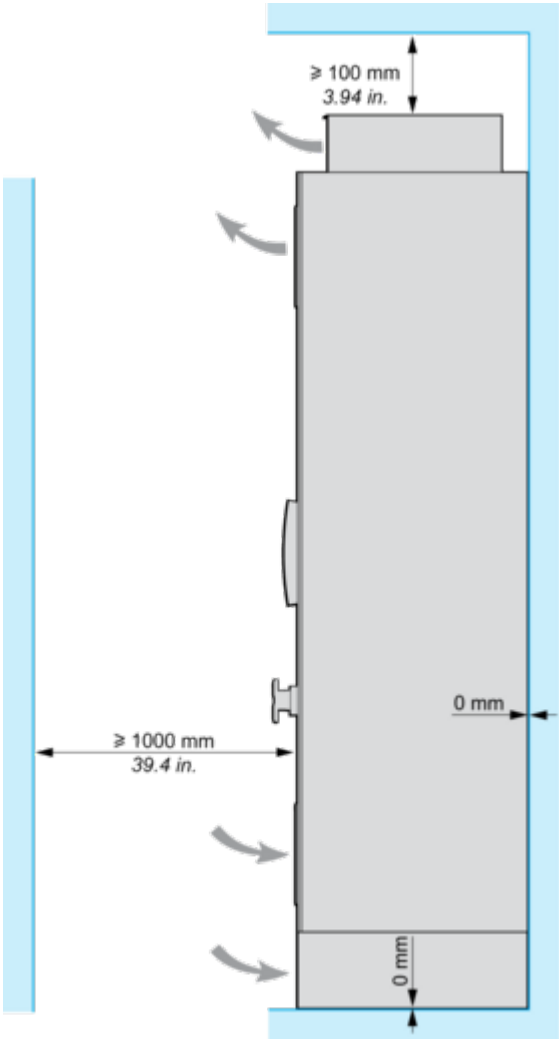


mm
in.



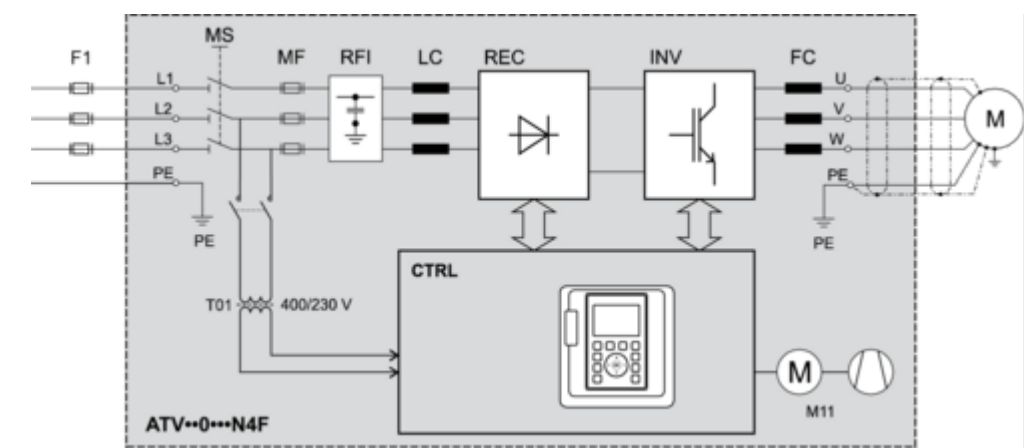
Mounting and Clearance

Clearances



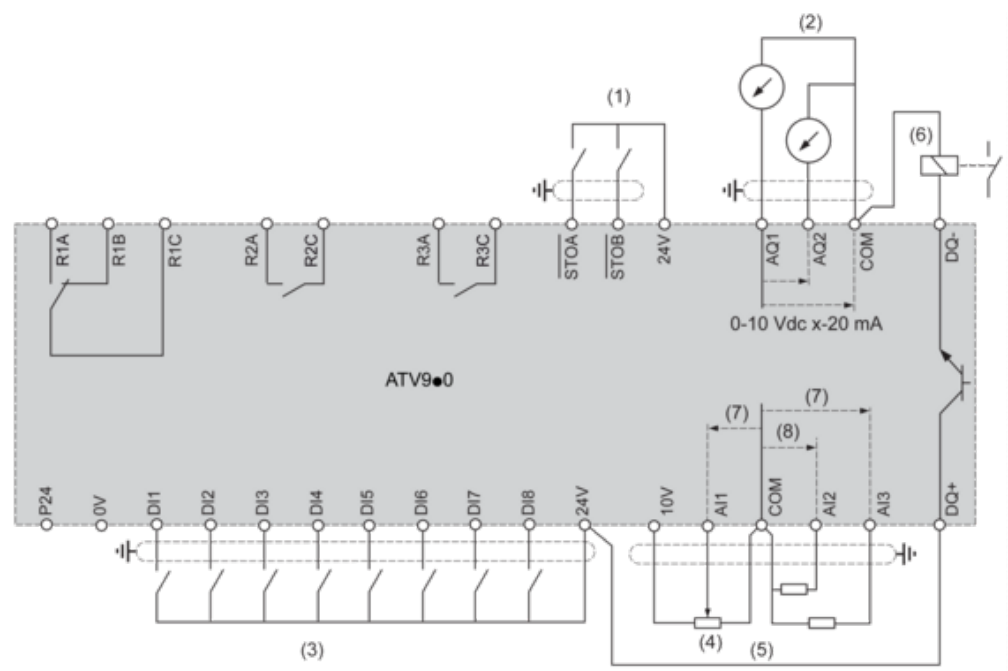
Connections and Schema

Floor Standing Drive Circuit Diagram



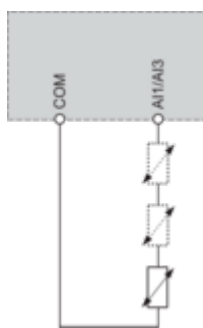
- F1** External pre-fuse or circuit breaker
- MS** Built-in main switch (only available on IP54 drives)
- T01** Control transformer 400 / 230 V AC
- MF** aR fuses
- RFI** Built-in RFI filter
- LC** Line reactor choke
- REC** Rectifier module
- INV** Inverter module
- FC** dv/dt filter (from 355 kW the dv/dt filter choke 150 m is built-in as standard)
- CTRL** Control panel
- M11** Fan in enclosure door

Control Block Wiring Diagram



- (1) Safe Torque Off
 - (2) Analog Output
 - (3) Digital Input
 - (4) Reference potentiometer
 - (5) Analog Input
 - (6) Digital Output
 - (7) 0-10 Vdc, x-20 mA
 - (8) 0-10 Vdc, -10 Vdc...+10 Vdc
- R1A, R1B, R1C :** Fault relay
R2A, R2C : Sequence relay
R3A, R3C : Sequence relay

Sensor Connection



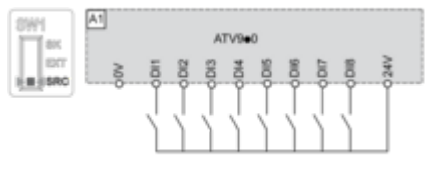
It is possible to connect either 1 or 3 sensors on terminals AI1 or AI3

Sink / Source Switch Configuration

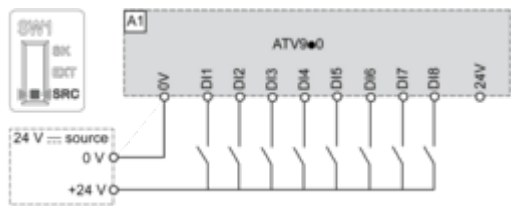
The switch is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

- Set the switch to Source (factory setting) if using PLC outputs with PNP transistors.
- Set the switch to Ext if using PLC outputs with NPN transistors.

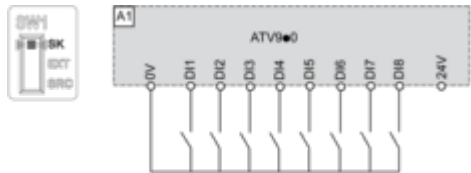
Switch Set to SRC (Source) Position Using the Output Power Supply for the Digital Inputs



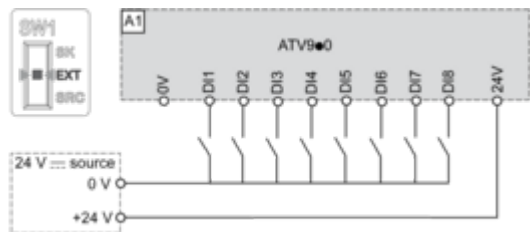
Switch Set to SRC (Source) Position and Use of an External Power Supply for the DI's



Switch Set to SK (Sink) Position Using the Output Power Supply for the Digital Inputs



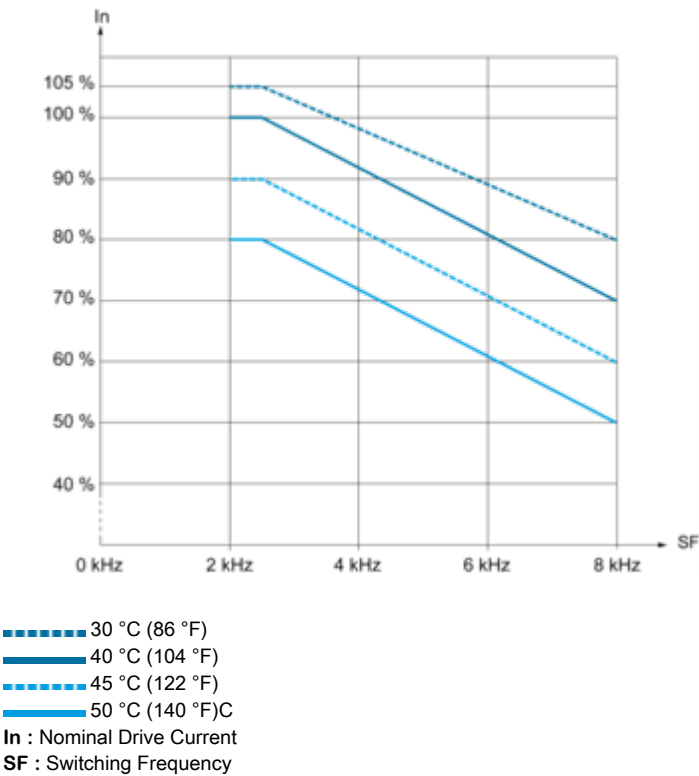
Switch Set to EXT Position Using an External Power Supply for the DI's



Performance Curves

Derating Curves

Normal Duty



Derating Curves

Heavy Duty

