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Data sheet for SINAMICS G120C

Article No. :

6SL3210-1KE26-0UF1



Figure similar

Client order no.
Order no. :
Offer no. :
Remarks :

Rated data		
Input		
Number of phases	3 AC	
Line voltage	380 480 V +1	0 % -20 %
Line frequency	47 63 Hz	
Rated current (LO)	53.00 A	
Rated current (HO)	44.00 A	
Output		
Number of phases	3 AC	
Rated voltage	400V IEC	480V NEC ¹⁾
Rated power (LO)	30.00 kW	30.00 hp
Rated power (HO)	22.00 kW	25.00 hp
Rated current (LO)	58.00 A	
Rated current (HO)	43.00 A	
Rated current (IN)	58.00 A	
Max. output current	87.00 A	
Pulse frequency	4 kHz	
Output frequency for vector control	0 240 Hz	
Output frequency for V/f control	0 550 Hz	

Overload capability

Low Overload (LO)

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

200% base load current IH for 3 s, followed by 150% base load current IH for 57 s in a 300 s cycle time

General tech. specifications		
Power factor λ	0.90 0.95	
Offset factor $\cos \phi$	0.99	
Efficiency η	0.98	
Sound pressure level (1m)	72 dB	
Power loss	1,040.0 W	
Filter class (integrated)	Unfiltered	
Communication		

Communication

PROFINET, EtherNet/IP

ltem no. : Consignment no. : Project :

Inputs / outputs			
Standard digital inputs			
Number	6		
Switching level: $0 \rightarrow 1$	11 V		
Switching level: $1 \rightarrow 0$	5 V		
Max. inrush current	15 mA		
Fail-safe digital inputs			
Number	1		
Digital outputs			
Number as relay changeover contact	1		
Output (resistive load)	DC 30 V, 0.5 A		
Number as transistor	1		
Output (resistive load)	DC 30 V, 0.5 A		
Analog / digital inputs			
Number	1 (Differential input)		
Resolution	10 bit		
Switching threshold as digital input			
0→1	4 V		
1→0	1.6 V		
Analog outputs			
Number	1 (Non-isolated output)		
PTC/ KTY interface			
1 motor temperature sensor input, sensors that can be connected PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\text{C}$			
Closed-loop cor	ntrol techniques		
V/f linear / square-law / parameterizable	Yes		
V/f with flux current control (FCC)	Yes		
V/f ECO linear / square-law	Yes		

V/f with flux current control (FCC)	Yes
V/f ECO linear / square-law	Yes
Sensorless vector control	Yes
Vector control, with sensor	No
Encoderless torque control	No
Torque control, with encoder	No

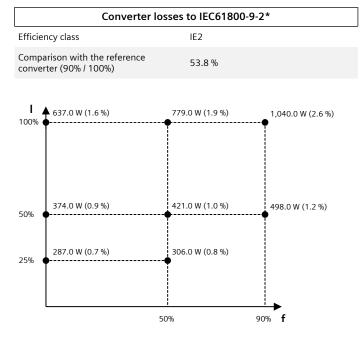
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Ambi	ent conditions		
Cooling	Air cooling using an integrated fan		
Cooling air requirement	0.055 m³/s (1.942 ft³/s)		
Installation altitude	1,000 m (3,280.84 ft)		
Ambient temperature			
Operation	-20 40 °C (-4 104 °F)		
Transport	-40 70 °C (-40 158 °F)		
Storage	-25 55 °C (-13 131 °F)		
Relative humidity			
Max. operation	95 % RH, condensation not permitted		
Connections			
Signal cable			
Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)		
Line side			
Version	screw-type terminal		
Conductor cross-section	10.00 35.00 mm² (AWG 8 AWG 2)		
Motor end			
Version	Screw-type terminals		
Conductor cross-section	10.00 35.00 mm ² (AWG 8 AWG 2)		
DC link (for braking resistor)			
Version	Screw-type terminals		
Conductor cross-section	10.00 35.00 mm² (AWG 8 AWG 2)		
Line length, max.	10 m (32.81 ft)		
PE connection	Screw-type terminals		
Max. motor cable length			
Shielded	200 m (656.17 ft)		
Unshielded	300 m (984.25 ft)		
Med	chanical data		
Degree of protection	IP20 / UL open type		
Frame size	FSD		
Net weight	17.10 kg (37.70 lb)		
Dimensions			
Width	200 mm (7.87 in)		
Height	472 mm (18.58 in)		
Depth	237 mm (9.33 in)		
	Standards		
Compliance with standards	CE, cUL, UL, KC, EAC, C-Tick (RCM)		
CE marking	EMC Directive 2004/108/EC, Low- Voltage Directive 2006/95/EC		



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

*calculated values

¹⁾The output current and HP ratings are valid for the voltage range 440V-480V